

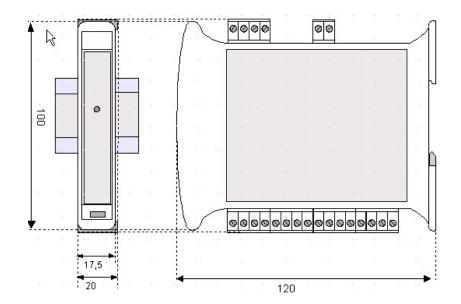
SmartMod <u>Analog Output Module</u>

HE359DAC201 0-10V 14-Bit Resolution



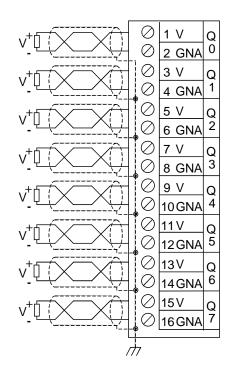
1 Specifications

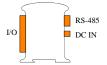
	DAC201			DAC201
Number of Channels	8	_	Thermal Drift	100ppm max
Output Ranges	0-10V		Terminal Type	Screw Type, Removable
Resolution	Approximately 14-Bit		Storage Temp.	-40° to 85° Celsius
Load Resistance	Voltage: >5Kohm		Operating Temp. Relative	-10° to 60° Celsius
Resistance	SOCOLILI		Humidity	5 to 95% Non- condensing
Output Calibration	Voltage: +/- 10mV		Dimensions WxHxD	17.5mm x 100mm x 120mm 0.69" x 3.94" x 4.72"
External Power Supply Voltage	18-30Vdc		Weight	150g (6 oz.)
Required Power (Steady State)	30mA @ 24Vdc, typical		Communications	Modbus/RTU (binary) RS-485 half duplex
Required Power (Inrush)	Negligible		Factory Default Communications Parameters	38400 baud, N, 8, 1, no h/s Default Modbus ID 1
Isolation	2000Vac for 60 seconds (Input/Power & Input/Comms)		Supported Modbus Commands (family)	1,2,3,4,5,6,8,1 5,16



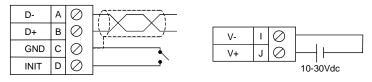
Dimensions in inches are 0.69"W x 3.95"H x 4.72"D Note: Number of I/O terminal connections vary from model to model

2 Wiring – I/O





Pin #	DAC201		Pin #	DAC201	
1	V	OUT 0	9	V	OUT 4
2	GNA	0010	10	GNA	0014
3	V	OUT 1	11	V	OUT 5
4	GNA	0011	12	GNA	0013
5	V	OUT 2	13	V	OUT 6
6	GNA	0012	14	GNA	0010
7	V	OUT 3	15	V	OUT 7
8	GNA	0013	16	GNA	0017



Wiring RS-485

Wiring DC IN

Notes:

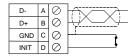
Both ends of the RS-485 network should be terminated with a 100ohm, 1/4W, 1% resistor. Many OCS controllers feature dip switches or jumpers which enable appropriate termination if the OCS is located on a network end.

MAN0839-03-EN Specifications / Installation

3 Init Default Setup

Communication parameters will be set to INIT default after performing the procedure:

- 1. Install jumper between INIT and GND terminals of the RS-485 port.
- 2. Apply power to Smartmod unit.
- 3. Read parameter words to see current parameters.
- 4. Write changes if necessary.



The Default Settings Are:

Modbus ID = 1 Baud rate = 9600 Parity = None Stop Bits = 1 Data Bits = 8 No handshake

Note: There are 2 types of default settings possible:

- 1. Factory default as described in section 1 (Specifications)
- 2. Default after INIT as described in section 3 (INIT Default Setup)

4 Configuration DATA

SmartMod Configuration settings are mapped into Modbus Register space. This configuration data may be modified with any Modbus/RTU Master device. For convenience, Horner APG has developed a variety of Cscape application files which allow an OCS (Xle, NX, LX, QX) to act as a SmartMod configurator. Initial configuration of SmartMod module should be done on an individual basis, since all modules come from the factory with a default Modbus ID of 1. Once each module on the network has its own unique Modbus ID, further configuration adjustments can be made with the entire network powered.

All configuration parameters listed below (except 40012 Channel Enable) are stored in EPROM. That means they should not be constantly rewritten.

Configuration Parameters – Registers 40001 through 40013						
Modbus Register	Description	Min	Max	Default		
40001- 40005	Reserved					
40006	Communications Parameters	See Table 1		38.4kbau d, N, 8, 1, RTU Mode		
40007	Modbus ID	1	255	1		
40008	Rx/Tx Delay (in 2mS steps)	0	255	0mS		
40009	Watchdog Timer (in 0.5s steps)	0	255	10 (5s)		
40010	Modbus Coil Data Not Configuration Data – See I/O Data					
40011	Reserved					
40012	Reserved					
40013	Reserved					
40014	Output Type	255	255	255 (All channel s Voltage)		

Register 40006 (Communications Parameters) Bit Definition								
Bits 7- 15	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Unused	Mode	Parity		Data Bits	Baud Rate			
	0 = ASCII	Value	Meaning $0 = 7$	0 = 7	Value	Mea	ning	
	Mode		0	Mark	Data	0	1200	baud
		1	Even	Bits	1	2400	baud	
	1 = RTU	2	Odd	1 = 8	2	4800	baud	
	Mode	3	Space	Data	3	9600	baud	
	Wode			Bits	4	19200) baud	
					5-7	38400) baud	

5 Input/Output DATA

SmartMod Analog I/O utilizes both Modbus Registers (40001-40030) and Coils (1-11). It is possible to access all data using Registers only, because the Coils can be accessed through Register 40010.

The following tables lists all Modbus I/O data available.

	I/O Register Data (Registers 40010-40026)						
Modbus Register	Description	Access	Minimum	Maximum	Units		
40010	Mirror of Coil Data	Read/Write	n/a	n/a	n/a		
40015	Output 0	Read/Write	0	10000	1mV		
40016	Output 2	Read/Write	0	10000	1mV		
40017	Output 4	Read/Write	0	10000	1mV		
40018	Output 6	Read/Write	0	10000	1mV		
40019	Output 1	Read/Write	0	10000	1mV		
40020	Output 3	Read/Write	0	10000	1mV		
40021	Output 5	Read/Write	0	10000	1mV		
40022	Output 7	Read/Write	0	10000	1mV		
40023	Default/Safe Value Out 0	Read/Write	0	10000	1mV		
40024	Default/Safe Value Out 1	Read/Write	0	10000	1mV		
40025	Default/Safe Value Out 2	Read/Write	0	10000	1mV		
40026	Default/Safe Value Out 3	Read/Write	0	10000	1mV		
40027	Default/Safe Value Out 4	Read/Write	0	10000	1mV		
40028	Default/Safe Value Out 5	Read/Write	0	10000	1mV		
40029	Default/Safe Value Out 6	Read/Write	0	10000	1mV		
40030	Default/Safe Value Out 7	Read/Write	0	10000	1mV		

Modbus Coil	Description	Access
00009	Watchdog Enabled	Read/Write
00010	Watchdog Event	Read/Write
00011	Power-up Event	Read/Write

Modbus Register	Description	Access
40010 bit 0	Watchdog Enabled	Read/Write
40010 bit 1	Watchdog Event	Read/Write
40010 bit 2	Power-up Event	Read/Write

Watchdog Event & Power-up Event Operation

If Coil 9 (Watchdog Enabled) is set, Coil 10 (Watchdog Event) will set if the Watchdog Timeout value is exceeded. The Watchdog Timeout value is set in Register 40009. When set, Coil 10 can be reset by the controller when normal communications resumes.

The Power-up Event (Coil 11) is set every time the power is applied. It can be cleared by the controller if desired.

6 Installation / safety

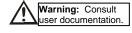
Warning: Remove power from the OCS controller, CAN port, and any peripheral equipment connected to this local system before adding or replacing this or any module.

- a. All applicable codes and standards should be followed in the installation of this product.
- b. Shielded, twisted-pair wiring should be used for best performance.
- c. Shields may be terminated at the module terminal strip.
- d. In severe applications, shields should be tied directly to the ground block within the panel.
- e. Use the following wire type or equivalent: Belden 8441.

For detailed installation and a <u>handy checklist</u> that covers panel box layout requirements and minimum clearances, refer to the hardware manual of the controller you are using.

When found on the product, the following symbols specify:





Technical Support

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